

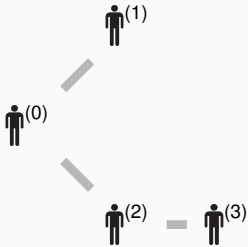
EIGHT(ISH) CHALLENGES IN (BAYESIAN) PHYLODYNAMICS, 11 YEARS LATER: REVISITING FROST *ET AL.* (2015)

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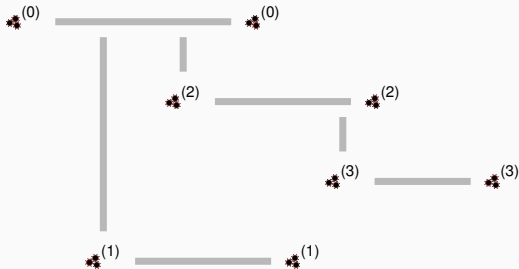
WHY PHYLODYNAMICS WORKS



Nonphylogenetic infection trees:

- Infections are nodes.
- Transmissions are edges.
- Direction of transmission is known.

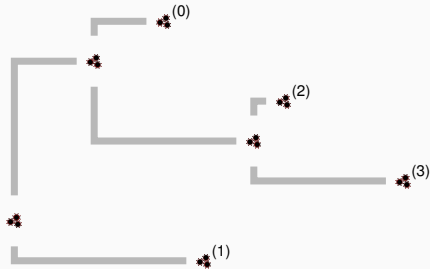
WHY PHYLODYNAMICS WORKS



Phylogenetic transmission trees:

- Infections are **edges**.
- Transmissions are **nodes**.
- Direction of transmission is known.

WHY PHYLODYNAMICS WORKS







Standard phylogenetic trees:

- Infections are edges.
- Transmissions are nodes.
- Direction of transmission is **unknown**.

$$\begin{aligned}
 \Pr(\text{person} \rightarrow \text{person}, \text{tree}, \text{matrix}, \text{pie chart} \mid \text{sequence}, \text{clock}) &\propto \Pr(\text{sequence}, \text{clock} \mid \text{tree}, \text{matrix}, \text{pie chart}) \\
 &\times \Pr(\text{tree}, \text{matrix}, \text{pie chart} \mid \text{person} \rightarrow \text{person}) \\
 &\times \Pr(\text{person} \rightarrow \text{person} \mid \mathcal{M})
 \end{aligned}$$

$$\begin{aligned}
 \Pr(\text{infection process}, \text{tree}, \text{substitution model}, \text{clock model} \mid \text{genetic data}, \text{clock}) &\propto \Pr(\text{genetic data}, \text{clock} \mid \text{tree}, \text{substitution model}, \text{clock}) \\
 &\times \Pr(\text{tree}, \text{substitution model}, \text{clock} \mid \text{infection process}) \\
 &\times \Pr(\text{infection process} \mid \mathcal{M})
 \end{aligned}$$

- The **posterior** distribution contains information about focal and nuisance parameters.
- Focal: infection process, .
- Nuisance: tree, , substitution model, , clock model, .

$$\begin{aligned}
 \Pr(\text{person} \rightarrow \text{person}, \text{tree}, \text{network}, \text{pie chart} \mid \text{matrix}, \text{microscope}) &\propto \Pr(\text{matrix}, \text{microscope} \mid \text{tree}, \text{network}, \text{pie chart}) \\
 &\times \Pr(\text{tree}, \text{network}, \text{pie chart} \mid \text{person} \rightarrow \text{person}) \\
 &\times \Pr(\text{person} \rightarrow \text{person} \mid \mathcal{M})
 \end{aligned}$$

- The **prior** distribution is where most phylodynamics lives.
- The phylodynamic prior, $\Pr(\text{person} \rightarrow \text{person} \mid \mathcal{M})$.
- The phylodynamic likelihood, $\Pr(\text{tree}, \text{network}, \text{pie chart} \mid \text{person} \rightarrow \text{person})$.

$$\begin{aligned}
 \Pr(\text{person} \rightarrow \text{person}, \text{tree}, \text{network}, \text{pie chart} \mid \text{matrix}, \text{microscope}) &\propto \Pr(\text{matrix}, \text{microscope} \mid \text{tree}, \text{network}, \text{pie chart}) \\
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$$\begin{aligned}
 \Pr(\text{👤} \rightarrow \text{👤}, \text{🌳}, \text{📊}, \text{🕒} \mid \text{📊}, \text{🕒}) &\propto \Pr(\text{📊}, \text{🕒} \mid \text{🌳}, \text{📊}, \text{🕒}) \\
 &\times \Pr(\text{🌳}, \text{📊}, \text{🕒} \mid \text{👤} \rightarrow \text{👤}) \\
 &\times \Pr(\text{👤} \rightarrow \text{👤} \mid \mathcal{M})
 \end{aligned}$$

- The **likelihood** bridges the tree and the genomic data.
- The phylogenetic likelihood, $\Pr(\text{📊} \mid \text{🌳}, \text{📊}, \text{🕒})$
- The likelihood of any data, 🕒 , for the phylodynamic model, such as geographic locations or sampling times.

EIGHT(ISH) CHALLENGES

Frost et al. (2015) list eight challenges to the field:

- Sampling patterns.
- Model realism.
- Stochastic effects.
- Population inhomogeneity.
- Recombination and reassortment.
- Phenotypic information.
- Multiscale modeling.
- Scalability and efficiency.

EIGHT(ISH) CHALLENGES

Frost et al. (2015) list eight challenges to the field:

- Sampling biases.
- Model adequacy.
- Stochastic effects.
- Population inhomogeneity.
- Recombination and reassortment.
- Data integration.
- Multiscale modeling.
- Scalability and efficiency.
- Realtime inference.

SAMPLING BIASES

Frost et al. (2015): temporal imbalance is problematic, especially for birth-death models.

Progress:

- Preferentially-sampled coalescents (Karcher et al. 2016).
- Time-varying birth-death models.
 - Let the sampling rate vary arbitrarily (Gavryushkina et al. 2014).
 - Bayesian regularization of the sampling rate (Magee et al. 2020).

Remaining challenges and open questions:

- Birth-death model nonidentifiability: MacPherson et al. (2022).
- Spatiotemporal variation.

Frost et al. (2015): geographic imbalance is problematic, especially for phylogeographic models.

Progress:

- Less than one might hope, but see case study.

Remaining challenges and open questions:

- Lack of data availability about sampling intensity.
- What do the models actually assume?

MODEL ADEQUACY

Frost et al. (2015):

- Our clock models are simplistic.
- Epidemiology and evolution are intertwined in unmodeled ways.
- We lack tractable models of trees under selection.

Progress:

- Flexible clock models (Bletsa et al. 2019; Membrebe et al. 2019).
- “Nonparametric” models for selection (Barido-Sottani et al. 2020; Maliet et al. 2019).

Remaining challenges and open questions:

- Immune-dependent models are hard and require data we lack.
- For most purposes, selective models are lacking.

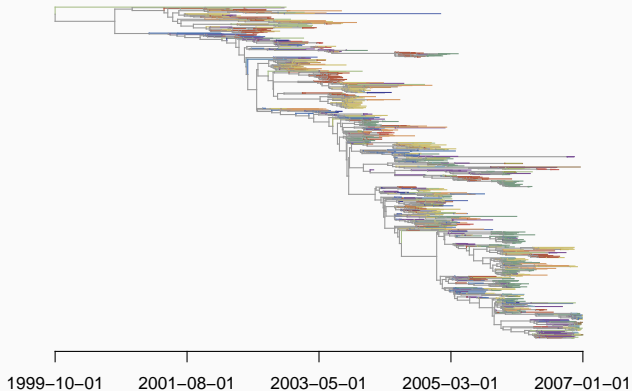
Realism for realism's sake is a trap.

- There are different kinds of wrongness.
 - Delineate focal and nuisance parameters.
 - Embrace (good) approximations (for the analysis regime).
- Don't fear the "non"s.
 - Nonmechanistic.
 - Nonparametric.
- The model just has to be good enough to answer your questions.

Understanding the dynamics of influenza A virus dispersal.

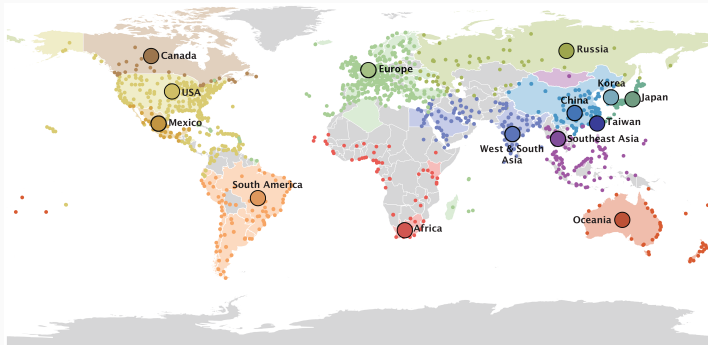
CASE STUDY: MODEL ADEQUACY AND SAMPLING BIASES

Understanding the dynamics of influenza A virus dispersal.



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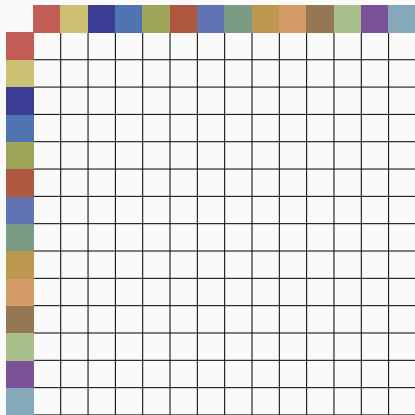


Understanding the dynamics of influenza A virus dispersal.

- Lemey et al. (2014) considered 22 potential drivers of spread.
- Across all analyses, air travel volume is most consistent predictor.
- Air travel was rarely the only supported predictor.
 - Possibly due to unmodeled sampling biases.

CASE STUDY: MODEL ADEQUACY AND SAMPLING BIASES

Understanding the dynamics of influenza A virus dispersal.



Understanding the dynamics of influenza A virus dispersal.

Q

GLM substitution models with random-effects.

$$\log(Q_{ij}) = \sum_k X_{ijk} \beta_k + \epsilon_{ij}$$

- Q_{ij} describes the instantaneous rate of spread from i to j .
- X_{ij} are observed covariates of spread.
- β describe how the covariates affect spread.
- ϵ add flexibility.

Understanding the dynamics of influenza A virus dispersal.

- Keep only best-supported covariate in GLM: air travel.
- Use random-effects to ask: what does air travel miss?

CASE STUDY: MODEL ADEQUACY AND SAMPLING BIASES

Understanding the dynamics of influenza A virus dispersal.



Unimportant, **equivocal support**, **unequivocal support**.

Frost et al. (2015):

- Most models use deterministic population dynamics.
- Linear birth-death models assume exponential growth.
- Nonlinear and mechanistic models are lacking.

Progress:

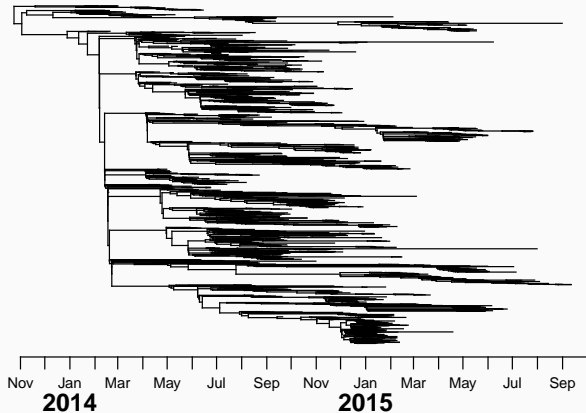
- Locally linear birth-death models (Shao et al. 2025; Magee et al. 2020).
- Adding mechanistic components to existing models (Tang et al. 2023).
- Particle filtering for fitting a wide range of models (King et al. 2025).

Remaining challenges and open questions:

- When can we ignore stochastic effects?
- Is there a happy medium?

CASE STUDY: STOCHASTIC EFFECTS

Border closures and transmission, 2014 West African Ebola epidemic.



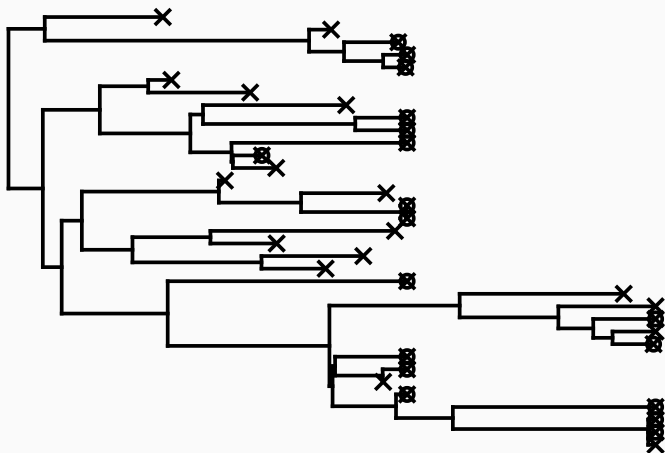
CASE STUDY: STOCHASTIC EFFECTS

Locally linear phylogenetic birth-death models, (Shao et al. 2024; Magee et al. 2020; Gavryushkina et al. 2014).

- New infections arise at time-varying birth rate $\lambda(t)$.
- Individuals become noninfectious at time-varying death rate $\mu(t)$.
- Samples are taken at time-varying rate $\rho(t)$.
 - Some proportion of these become noninfectious, $\nu(t)$.
- Effective reproduction number: $R_e(t) = \lambda(t)/(\mu(t) + \nu(t))$

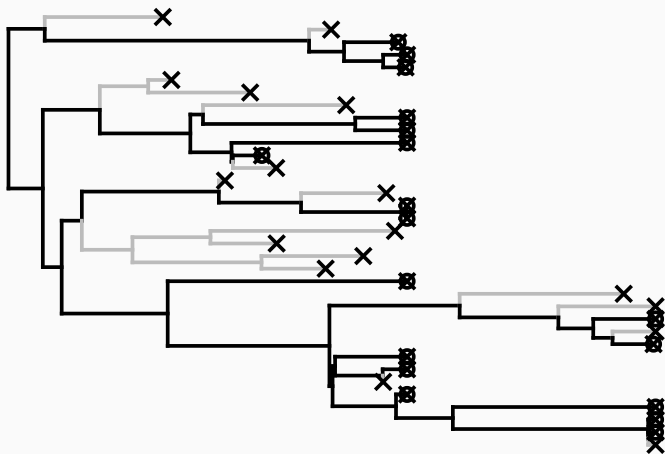
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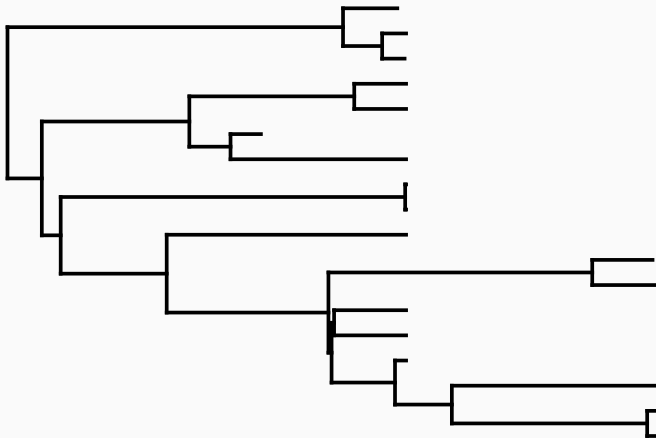
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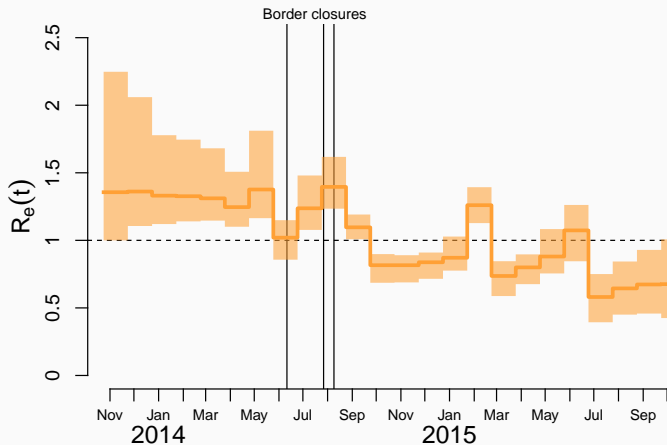


Locally linear phylogenetic birth-death models, (Shao et al. 2024; Magee et al. 2020; Gavryushkina et al. 2014).

- Simplifying assumption: rates are piecewise constant.
 - Monthly scale.
 - Duration of infection roughly 15-17 days (Van Kerkhove et al. 2015).

CASE STUDY: STOCHASTIC EFFECTS

Border closures and transmission, 2014 West African Ebola epidemic.



Frost et al. (2015): populations are not panmictic.

Progress: the structured coalescent

- Tractable approximations (De Maio et al. 2015; Müller et al. 2017).
- Efficient inference (Shao et al. 2025; Vaughan et al. 2014).

Remaining challenges and open questions:

- These models are intensely demanding.
- Multi-type phylogenetic birth-death models exist, but are unused.

Frost et al. (2015): high variance in contacts, *i.e.* superspreading, is challenging.

Progress:

- Λ - and Beta-coalescents, (Hoscheit et al. 2019; Zhang et al. 2025).
- Lineage-dependent birth-death models, (Barido-Sottani et al. 2020; Maliet et al. 2019).

Remaining challenges and open questions:

- Computational intensity of lineage-dependent birth-death models.
- What can we actually infer with these models?
- Does sampling intensity affect their necessity?

Frost et al. (2015): recombination is hard and oft ignored.

Progress:

- Inference of ancestral recombination graphs (ARGs) (Müller et al. 2022).
- Efficient data structures (Ralph et al. 2020).

Remaining challenges and open questions:

- Treespace is massive and gnarly. ARGspace is bigger and gnarlier.

Frost et al. (2015): phenotype can be informative about transmission and ought to be modeled.

Progress:

- Linking lab measurements to phylogenies via experimental codon models (Hilton et al. 2018; Bloom 2014).
- Linking case data and phylogenies (Gupta et al. 2020).
- Much more, see Hassler et al. (2023) for a review.

Remaining challenges and open questions:

- Modular, comprehensive, user-friendly options.

Frost et al. (2015): branching events in a population-level phylogeny are not actually transmission events.

Progress:

- Joint inference of phylogenetic and transmission tree (Klinkenberg et al. 2017).
- Bottleneck models (Hall et al. 2019).
- Quantifying different between and within host dynamics, (Vrancken et al. 2017).

Remaining challenges and open questions:

- Tree within a tree models are demanding.
- How bad of an approximation is it to ignore that?

Frost et al. (2015): big phylogenies pose big problems.

Progress:

- Parsimony(-based approximations) (Turakhia et al. 2021; De Maio et al. 2023).
- Gradient-based inference (Ji et al. 2020; Magee et al. 2024).
- Non-traditional tree inference (Zhang et al. 2024)

Remaining challenges and open questions:

- Parsimony likely only works well in the near-perfect regime (Wertheim et al. 2022).
- Trees are still the bottleneck and stubbornly resistant to alternative inference techniques.

A tale of two substitution models (Magee et al. 2024).

A tale of two substitution models (Magee et al. 2024).

- Inferring substitution dynamics and a 583-sequence tree of SARS-CoV-2 (Pekar et al. 2022).
- Inferring phylogeographic dispersal among 1441 sequences of influenza A virus (H3N2) (Lemey et al. 2014).

Approximate substitution model gradients

$$\frac{\partial \Pr(\mathbf{I} | \mathbf{E}^E, \mathbf{I}^I)}{\partial \mathbf{I}^I_{ij}} = \sum_{\mathbf{E}^E} \frac{\partial \Pr(\mathbf{I} | \mathbf{E}^E, \mathbf{I}^I)}{\partial \mathbf{I}^I_{ij}}$$

An aside on partial likelihoods.

$$\Pr\left(\begin{array}{c} \text{A} \\ \text{A} \\ \text{A} \\ \text{T} \end{array} \mid \begin{array}{c} \text{E} \\ \text{E} \\ \text{E} \end{array}, \begin{array}{cc} \text{A} & \text{C} \\ \updownarrow & \updownarrow \\ \text{G} & \text{T} \end{array}\right)$$

CASE STUDY: SCALABILITY AND EFFICIENCY

An aside on partial likelihoods.

$$\begin{bmatrix} \Pr(\text{A} | \text{tree}, \text{matrix}, \text{A}) \\ \Pr(\text{C} | \text{tree}, \text{matrix}, \text{C}) \\ \Pr(\text{G} | \text{tree}, \text{matrix}, \text{G}) \\ \Pr(\text{T} | \text{tree}, \text{matrix}, \text{T}) \end{bmatrix}^T$$

postorder partial
likelihood vector



$$\left(e^{\text{matrix} \times I} \right)^T$$

$$\begin{bmatrix} \Pr(\text{A} | \text{matrix}, \text{tree}) \\ \Pr(\text{C} | \text{matrix}, \text{tree}) \\ \Pr(\text{G} | \text{matrix}, \text{tree}) \\ \Pr(\text{T} | \text{matrix}, \text{tree}) \end{bmatrix}$$

pre-preorder partial
likelihood vector



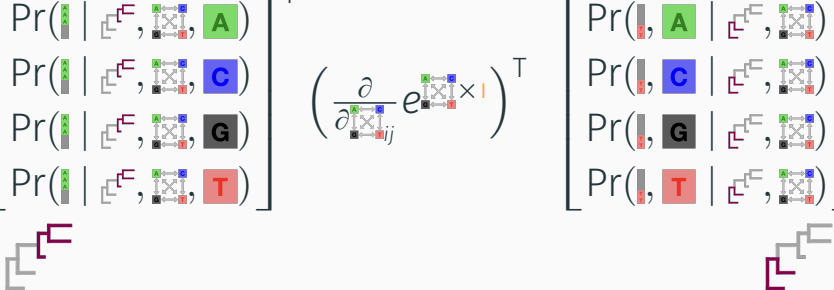
CASE STUDY: SCALABILITY AND EFFICIENCY

The gradient on a single branch.

$$\frac{\partial \Pr(\begin{array}{c} \text{A} \\ \text{A} \\ \text{A} \\ \text{T} \end{array} | \begin{array}{c} \text{E} \\ \text{E} \\ \text{E} \\ \text{E} \end{array}, \begin{array}{cc} \text{A} & \text{C} \\ \updownarrow & \updownarrow \\ \text{G} & \text{T} \end{array})}{\partial \begin{array}{cc} \text{A} & \text{C} \\ \updownarrow & \updownarrow \\ \text{G} & \text{T} \end{array} ij}$$

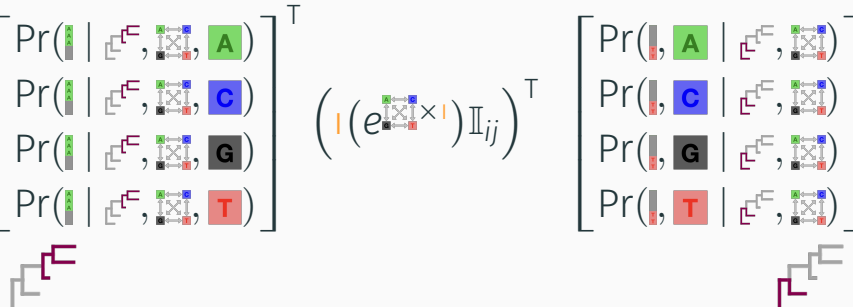
CASE STUDY: SCALABILITY AND EFFICIENCY

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$$\begin{bmatrix} \Pr(\text{A} | \text{tree}, \text{graph}, \text{A}) \\ \Pr(\text{C} | \text{tree}, \text{graph}, \text{C}) \\ \Pr(\text{G} | \text{tree}, \text{graph}, \text{G}) \\ \Pr(\text{T} | \text{tree}, \text{graph}, \text{T}) \end{bmatrix}^T \left(\frac{\partial}{\partial x_{ij}} e^{\text{graph} \times I} \right)^T \begin{bmatrix} \Pr(\text{A} | \text{tree}, \text{graph}) \\ \Pr(\text{C} | \text{tree}, \text{graph}) \\ \Pr(\text{G} | \text{tree}, \text{graph}) \\ \Pr(\text{T} | \text{tree}, \text{graph}) \end{bmatrix}$$


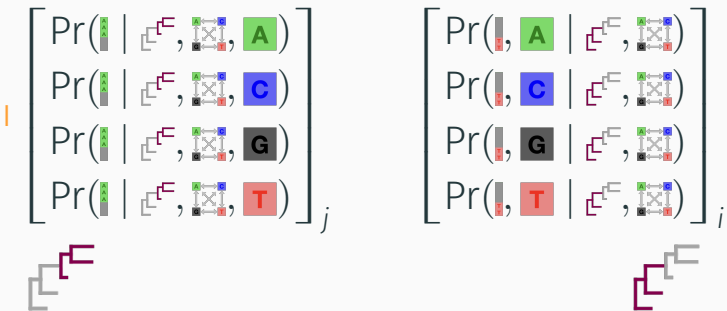
CASE STUDY: SCALABILITY AND EFFICIENCY

The (approximate) gradient on a single branch.

$$\begin{bmatrix} \Pr(\text{ } | \text{ } , \text{ } , \mathbf{A}) \\ \Pr(\text{ } | \text{ } , \text{ } , \mathbf{C}) \\ \Pr(\text{ } | \text{ } , \text{ } , \mathbf{G}) \\ \Pr(\text{ } | \text{ } , \text{ } , \mathbf{T}) \end{bmatrix}^T \left(\text{ } (e^{\text{ } \times \text{ } }) \mathbb{I}_{ij} \right)^T \begin{bmatrix} \Pr(\text{ } , \mathbf{A} | \text{ } , \text{ }) \\ \Pr(\text{ } , \mathbf{C} | \text{ } , \text{ }) \\ \Pr(\text{ } , \mathbf{G} | \text{ } , \text{ }) \\ \Pr(\text{ } , \mathbf{T} | \text{ } , \text{ }) \end{bmatrix}$$


CASE STUDY: SCALABILITY AND EFFICIENCY

The (approximate) gradient on a single branch.

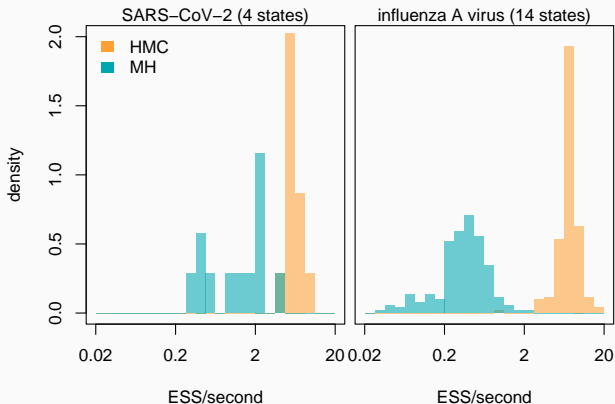
$$\left[\begin{array}{l} \Pr(\text{A} | \text{tree}_j, \text{A}) \\ \Pr(\text{C} | \text{tree}_j, \text{C}) \\ \Pr(\text{G} | \text{tree}_j, \text{G}) \\ \Pr(\text{T} | \text{tree}_j, \text{T}) \end{array} \right]_j \quad \left[\begin{array}{l} \Pr(\text{A} | \text{tree}_i, \text{A}) \\ \Pr(\text{C} | \text{tree}_i, \text{C}) \\ \Pr(\text{G} | \text{tree}_i, \text{G}) \\ \Pr(\text{T} | \text{tree}_i, \text{T}) \end{array} \right]_i$$


Inference using our approximate substitution gradient is highly efficient.

- Our approximation ($\mathcal{O}(ns^2)$) enables 1M MCMC samples in 1 hour for both analyses.
- With naïve gradients ($\mathcal{O}(ns^5)$), equivalent analyses take:
 - Influenza A virus phylogeography: 3 months.
 - SARS-CoV-2 substitution dynamics: 3 days.
- Without gradients, equivalent analyses take:
 - Influenza A virus phylogeography: 1.4 days.
 - SARS-CoV-2 substitution dynamics: 15 hours.

CASE STUDY: SCALABILITY AND EFFICIENCY

Inference using our approximate substitution gradient is highly efficient.



What does this approximate gradient actually get us?

- For high dimensional models, maybe a lot.
 - Days to hours can the difference between infeasible and feasible.
- For low-dimensional models, not so much.
 - DNA substitution models aren't really a bottleneck.
 - Original Lemey et al. (2014) used simpler models which converged faster.
- Tree inference is costly.
 - SARS-CoV-2 joint analysis takes about a week.

Key challenges

- Necessary infrastructure is extensive.
- Data incompleteness is time-varying.
- Models need to be sufficiently predictive.
- Tree inference is still slow in the general case.

Some successes

- The USHER SARS-CoV-2 tree.
- NextStrain.

Open questions:

- Can we do realtime Bayesian phylogenetic inference?
- How can we reward key providers of bioinformatics infrastructure?

CONCLUSIONS

Lots of progress since 2015.

- More and better models.
- Greatly expanded data integration.
- Major improvements in scalability and efficiency.

Many important models fall between

- Computationally burdensome.
- Essentially intractable.

Fast Bayesian inference of phylogenies remains a holy grail.

WHERE DO WE GO FROM HERE?

Tractable **general** solutions may be more robust than realistic.

- Non- or semi-mechanistic.
- Non- or semi-parametric.




Tractable **specific** solutions may

- Leverage clever mathematical tricks (Bryant et al. 2026).
- Likely rely on clever (or even dumb) approximations.


Some problems may need to be solved at other levels.

- Better **surveillance systems** beat better sampling models.






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